

**TABLE 8.5 Shear, moment, slope, and deflection formulas for finite-length beams on elastic foundations**

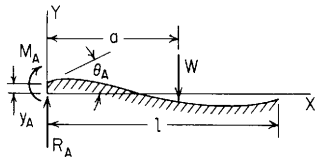
NOTATION:  $W$  = load (force);  $w$  = unit load (force per unit length);  $M_o$  = applied couple (force-length);  $\theta_o$  = externally created concentrated angular displacement (radians);  $\Delta_o$  = externally created concentrated lateral displacement (length);  $\gamma$  = temperature coefficient of expansion (unit strain per degree);  $T_1$  and  $T_2$  = temperatures on top and bottom surfaces, respectively (degrees).  $R_A$  and  $R_B$  are the vertical end reactions at the left and right, respectively, and are positive upward.  $M_A$  and  $M_B$  are the reaction end moments at the left and right, respectively, and all moments are positive when producing compression on the upper portion of the beam cross section. The transverse shear force  $V$  is positive when acting upward on the left end of a portion of the beam. All applied loads, couples, and displacements are positive as shown. All slopes are in radians, and all temperatures are in degrees. All deflections are positive upward and slopes positive when up and to the right. Note that  $M_A$  and  $R_A$  are reactions, not applied loads. They exist only when necessary end restraints are provided.

The following constants and functions, involving both beam constants and foundation constants, are hereby defined in order to permit condensing the tabulated formulas which follow

$k_o$  = foundation modulus (unit stress per unit deflection);  $b_o$  = beam width; and  $\beta = (b_o k_o / 4EI)^{1/4}$ . (Note: See page 131 for a definition of  $\langle x - a \rangle^n$ .) The functions  $\cosh \beta(x - a)$ ,  $\sinh \beta(x - a)$ ,  $\cos \beta(x - a)$ , and  $\sin \beta(x - a)$  are also defined as having a value of zero if  $x < a$ .

|  |  |  |
|--|--|--|
| $F_1 = \cosh \beta x \cos \beta x$   | $C_1 = \cosh \beta l \cos \beta l$   | $C_{11} = \sinh^2 \beta l - \sin^2 \beta l$                        |
| $F_2 = \cosh \beta x \sin \beta x + \sinh \beta x \cos \beta x$  | $C_2 = \cosh \beta l \sin \beta l + \sinh \beta l \cos \beta l$                        | $C_{12} = \cosh \beta l \sinh \beta l + \cos \beta l \sin \beta l$ |
| $F_3 = \sinh \beta x \sin \beta x$   | $C_3 = \sinh \beta l \sin \beta l$   | $C_{13} = \cosh \beta l \sinh \beta l - \cos \beta l \sin \beta l$ |
| $F_4 = \cosh \beta x \sin \beta x - \sinh \beta x \cos \beta x$  | $C_4 = \cosh \beta l \sin \beta l - \sinh \beta l \cos \beta l$                        | $C_{14} = \sinh^2 \beta l + \sin^2 \beta l$                        |
| $F_{a1} = \langle x - a \rangle^0 \cosh \beta \langle x - a \rangle \cos \beta \langle x - a \rangle$  | $C_{a1} = \cosh \beta(l - a) \cos \beta(l - a)$  |  |
| $F_{a2} = \cosh \beta(x - a) \sin \beta \langle x - a \rangle + \sinh \beta \langle x - a \rangle \cos \beta \langle x - a \rangle$                | $C_{a2} = \cosh \beta(l - a) \sin \beta(l - a) + \sinh \beta(l - a) \cos \beta(l - a)$ |  |
| $F_{a3} = \sinh \beta \langle x - a \rangle \sin \beta \langle x - a \rangle$  | $C_{a3} = \sinh \beta(l - a) \sin \beta(l - a)$  |  |
| $F_{a4} = \cosh \beta \langle x - a \rangle \sin \beta \langle x - a \rangle - \sinh \beta \langle x - a \rangle \cos \beta \langle x - a \rangle$ | $C_{a4} = \cosh \beta(l - a) \sin \beta(l - a) - \sinh \beta(l - a) \cos \beta(l - a)$ |  |
| $F_{a5} = \langle x - a \rangle^0 - F_{a1}$  | $C_{a5} = 1 - C_{a1}$  |  |
| $F_{a6} = 2\beta \langle x - a \rangle \langle x - a \rangle^0 - F_{a2}$   | $C_{a6} = 2\beta(l - a) - C_{a2}$  |  |

1. Concentrated intermediate load



$$\text{Transverse shear} = V = R_A F_1 - \gamma_A 2EI\beta^2 F_2 - \theta_A 2EI\beta^2 F_3 - M_A \beta F_4 - W F_{a1}$$

$$\text{Bending moment} = M = M_A F_1 + \frac{R_A}{2\beta} F_2 - \gamma_A 2EI\beta^2 F_3 - \theta_A EI\beta F_4 - \frac{W}{2\beta} F_{a2}$$

$$\text{Slope} = \theta = \theta_A F_1 + \frac{M_A}{2EI\beta} F_2 + \frac{R_A}{2EI\beta^2} F_3 - \gamma_A \beta F_4 - \frac{W}{2EI\beta^2} F_{a3}$$

$$\text{Deflection} = y = \gamma_A F_1 + \frac{\theta_A}{2\beta} F_2 + \frac{M_A}{2EI\beta^2} F_3 + \frac{R_A}{4EI\beta^3} F_4 - \frac{W}{4EI\beta^3} F_{a4}$$

If  $\beta l > 6$ , see Table 8.6

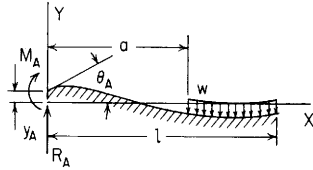
Expressions for  $R_A$ ,  $M_A$ ,  $\theta_A$ , and  $\gamma_A$  are found below for several combinations of end restraints

TABLE 8.5 Shear, moment, slope, and deflection formulas for finite-length beams on elastic foundations (*Continued*)

|                  | Right end   | Free   | Guided   | Simply supported  | Fixed   |   |
|------------------|---|--|--|---|---|---|
| Left end         | $R_A = 0$   | $M_A = 0$  | $R_A = 0$  | $M_A = 0$   | $R_A = 0$   | $M_A = 0$   |
| Free             | $\theta_A = \frac{W}{2EI\beta^2} \frac{C_2 C_{a2} - 2C_3 C_{a1}}{C_{11}}$ | $\theta_A = \frac{W}{2EI\beta^2} \frac{C_2 C_{a3} - C_4 C_{a1}}{C_{12}}$ | $\theta_A = \frac{W}{2EI\beta^2} \frac{C_1 C_{a2} + C_3 C_{a4}}{C_{13}}$ | $\theta_A = \frac{W}{2EI\beta^2} \frac{2C_1 C_{a3} + C_4 C_{a4}}{2 + C_{11}}$ | $\theta_A = \frac{W}{2EI\beta^2} \frac{2C_1 C_{a3} + C_4 C_{a4}}{2 + C_{11}}$ | $\theta_A = \frac{W}{2EI\beta^2} \frac{2C_1 C_{a3} + C_4 C_{a4}}{2 + C_{11}}$ |
|                  | $y_A = \frac{W}{2EI\beta^3} \frac{C_4 C_{a1} - C_3 C_{a2}}{C_{11}}$       | $y_A = \frac{-W}{2EI\beta^3} \frac{C_1 C_{a1} + C_3 C_{a3}}{C_{12}}$     | $y_A = \frac{-W}{4EI\beta^3} \frac{C_4 C_{a4} + C_2 C_{a2}}{C_{13}}$     | $y_A = \frac{W}{2EI\beta^3} \frac{C_1 C_{a4} - C_2 C_{a3}}{2 + C_{11}}$       | $y_A = \frac{W}{2EI\beta^3} \frac{C_1 C_{a4} - C_2 C_{a3}}{2 + C_{11}}$       | $y_A = \frac{W}{2EI\beta^3} \frac{C_1 C_{a4} - C_2 C_{a3}}{2 + C_{11}}$       |
| Guided           | $R_A = 0$   | $\theta_A = 0$   | $R_A = 0$  | $\theta_A = 0$  | $R_A = 0$   | $\theta_A = 0$  |
|                  | $M_A = \frac{W}{2\beta} \frac{C_2 C_{a2} - 2C_3 C_{a1}}{C_{12}}$          | $M_A = \frac{W}{2\beta} \frac{C_2 C_{a3} - C_4 C_{a1}}{C_{14}}$          | $M_A = \frac{W}{2\beta} \frac{C_1 C_{a2} + C_3 C_{a4}}{1 + C_{11}}$      | $M_A = \frac{W}{2\beta} \frac{2C_1 C_{a3} + C_4 C_{a4}}{1 + C_{11}}$          | $M_A = \frac{W}{2\beta} \frac{2C_1 C_{a3} + C_4 C_{a4}}{1 + C_{11}}$          | $M_A = \frac{W}{2\beta} \frac{2C_1 C_{a3} + C_4 C_{a4}}{1 + C_{11}}$          |
| Simply supported | $M_A = 0$   | $y_A = 0$  | $M_A = 0$  | $y_A = 0$   | $M_A = 0$   | $y_A = 0$   |
|                  | $R_A = W \frac{C_3 C_{a2} - C_4 C_{a1}}{C_{13}}$                          | $R_A = W \frac{C_1 C_{a1} + C_3 C_{a3}}{1 + C_{11}}$                     | $R_A = W \frac{C_1 C_{a1} + C_3 C_{a3}}{1 + C_{11}}$                     | $R_A = \frac{W}{2} \frac{C_2 C_{a2} + C_4 C_{a4}}{C_{14}}$                    | $R_A = W \frac{C_2 C_{a3} - C_1 C_{a4}}{C_{13}}$                              | $R_A = W \frac{C_2 C_{a3} - C_1 C_{a4}}{C_{13}}$                              |
| Fixed            | $\theta_A = 0$  | $y_A = 0$  | $\theta_A = 0$   | $y_A = 0$   | $\theta_A = 0$  | $y_A = 0$   |
|                  | $R_A = W \frac{2C_1 C_{a1} + C_4 C_{a2}}{2 + C_{11}}$                     | $R_A = W \frac{C_4 C_{a3} + C_2 C_{a1}}{C_{12}}$                         | $R_A = W \frac{C_4 C_{a3} + C_2 C_{a1}}{C_{12}}$                         | $R_A = W \frac{C_3 C_{a2} - C_1 C_{a4}}{C_{13}}$                              | $R_A = W \frac{2C_3 C_{a3} - C_2 C_{a4}}{C_{11}}$                             | $R_A = W \frac{2C_3 C_{a3} - C_2 C_{a4}}{C_{11}}$                             |
|                  | $M_A = \frac{W}{\beta} \frac{C_1 C_{a2} - C_2 C_{a1}}{2 + C_{11}}$        | $M_A = \frac{W}{\beta} \frac{C_1 C_{a3} - C_3 C_{a1}}{C_{12}}$           | $M_A = \frac{W}{\beta} \frac{C_1 C_{a3} - C_3 C_{a1}}{C_{12}}$           | $M_A = \frac{W}{2\beta} \frac{C_2 C_{a4} - C_4 C_{a2}}{C_{13}}$               | $M_A = \frac{W}{\beta} \frac{C_3 C_{a4} - C_4 C_{a3}}{C_{11}}$                | $M_A = \frac{W}{\beta} \frac{C_3 C_{a4} - C_4 C_{a3}}{C_{11}}$                |

**TABLE 8.5 Shear, moment, slope, and deflection formulas for finite-length beams on elastic foundations (Continued)**

2. Partial uniformly distributed load



$$\text{Transverse shear} = V = R_A F_1 - y_A 2EI\beta^3 F_2 - \theta_A 2EI\beta^2 F_3 - M_A \beta F_4 - \frac{w}{2\beta} F_{a2}$$

$$\text{Bending moment} = M = M_A F_1 + \frac{R_A}{2\beta} F_2 - y_A 2EI\beta^2 F_3 - \theta_A EI\beta F_4 - \frac{w}{2\beta^2} F_{a3}$$

$$\text{Slope} = \theta = \theta_A F_1 + \frac{M_A}{2EI\beta} F_2 + \frac{R_A}{2EI\beta^2} F_3 - y_A \beta F_4 - \frac{w}{4EI\beta^3} F_{a4}$$

$$\text{Deflection} = y = y_A F_1 + \frac{\theta_A}{2\beta} F_2 + \frac{M_A}{2EI\beta^2} F_3 + \frac{R_A}{4EI\beta^3} F_4 - \frac{w}{4EI\beta^4} F_{a5}$$

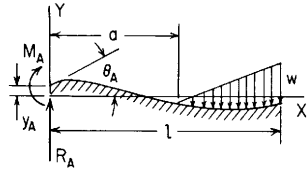
If  $\beta l > 6$ , see Table 8.6

Expressions for  $R_A$ ,  $M_A$ ,  $\theta_A$ , and  $y_A$  are found below for several combinations of end restraints

|                  | Right end   | Free           | Guided   | Simply supported   | Fixed  |                |
|------------------|---|----------------|--|--|--|----------------|
| Left end         | $R_A = 0$   | $M_A = 0$      | $R_A = 0$  | $M_A = 0$  | $R_A = 0$  | $M_A = 0$      |
|                  | $\theta_A = \frac{w}{2EI\beta^3} \frac{C_2 C_{a3} - C_3 C_{a2}}{C_{11}}$  |                | $\theta_A = \frac{w}{4EI\beta^3} \frac{C_2 C_{a4} - C_4 C_{a2}}{C_{12}}$     | $\theta_A = \frac{w}{2EI\beta^3} \frac{C_1 C_{a3} + C_3 C_{a5}}{C_{13}}$ | $\theta_A = \frac{w}{2EI\beta^3} \frac{C_1 C_{a4} + C_4 C_{a5}}{2 + C_{11}}$ |                |
| Free             | $y_A = \frac{w}{4EI\beta^4} \frac{C_4 C_{a2} - 2C_3 C_{a3}}{C_{11}}$      |                | $y_A = \frac{-w}{4EI\beta^4} \frac{C_1 C_{a2} + C_3 C_{a4}}{C_{12}}$         | $y_A = \frac{-w}{4EI\beta^4} \frac{C_4 C_{a5} + C_2 C_{a3}}{C_{13}}$     | $y_A = \frac{w}{4EI\beta^4} \frac{2C_1 C_{a5} - C_2 C_{a4}}{2 + C_{11}}$     |                |
|                  | $R_A = 0$   | $\theta_A = 0$ | $R_A = 0$  | $\theta_A = 0$   | $R_A = 0$  | $\theta_A = 0$ |
| Guided           | $M_A = \frac{w}{2\beta^2} \frac{C_2 C_{a3} - C_3 C_{a2}}{C_{12}}$         |                | $M_A = \frac{w}{4\beta^2} \frac{C_2 C_{a4} - C_4 C_{a2}}{C_{14}}$            | $M_A = \frac{w}{2\beta^2} \frac{C_1 C_{a3} + C_3 C_{a5}}{1 + C_{11}}$    | $M_A = \frac{w}{2\beta^2} \frac{C_1 C_{a4} + C_4 C_{a5}}{C_{12}}$            |                |
|                  | $y_A = \frac{-w}{4EI\beta^4} \frac{C_1 C_{a2} + C_4 C_{a3}}{C_{12}}$      |                | $y_A = \frac{-w}{8EI\beta^4} \frac{C_2 C_{a2} + C_4 C_{a4}}{C_{14}}$         | $y_A = \frac{w}{4EI\beta^4} \frac{C_1 C_{a5} - C_3 C_{a3}}{1 + C_{11}}$  | $y_A = \frac{w}{4EI\beta^4} \frac{C_2 C_{a5} - C_3 C_{a4}}{C_{12}}$          |                |
| Simply supported | $M_A = 0$   | $y_A = 0$      | $M_A = 0$  | $y_A = 0$  | $M_A = 0$  | $y_A = 0$      |
|                  | $R_A = \frac{w}{2\beta} \frac{2C_2 C_{a3} - C_4 C_{a2}}{C_{13}}$          |                | $R_A = \frac{w}{2\beta} \frac{C_1 C_{a2} + C_3 C_{a4}}{1 + C_{11}}$          | $R_A = \frac{w}{2\beta} \frac{C_2 C_{a3} + C_4 C_{a5}}{C_{14}}$          | $R_A = \frac{w}{2\beta} \frac{C_2 C_{a4} - 2C_1 C_{a5}}{C_{13}}$             |                |
|                  | $\theta_A = \frac{w}{4EI\beta^3} \frac{2C_1 C_{a3} - C_2 C_{a2}}{C_{13}}$ |                | $\theta_A = \frac{w}{4EI\beta^3} \frac{C_1 C_{a4} - C_3 C_{a2}}{1 + C_{11}}$ | $\theta_A = \frac{w}{4EI\beta^3} \frac{C_2 C_{a5} - C_4 C_{a3}}{C_{14}}$ | $\theta_A = \frac{w}{4EI\beta^3} \frac{2C_3 C_{a5} - C_4 C_{a4}}{C_{13}}$    |                |
| Fixed            | $\theta_A = 0$  | $y_A = 0$      | $\theta_A = 0$   | $y_A = 0$  | $\theta_A = 0$   | $y_A = 0$      |
|                  | $R_A = \frac{w}{\beta} \frac{C_1 C_{a2} + C_4 C_{a3}}{2 + C_{11}}$        |                | $R_A = \frac{w}{2\beta} \frac{C_4 C_{a4} + C_2 C_{a2}}{C_{12}}$              | $R_A = \frac{w}{\beta} \frac{C_3 C_{a3} - C_1 C_{a5}}{C_{13}}$           | $R_A = \frac{w}{\beta} \frac{C_3 C_{a4} - C_2 C_{a5}}{C_{11}}$               |                |
|                  | $M_A = \frac{w}{2\beta^2} \frac{2C_1 C_{a3} - C_2 C_{a2}}{2 + C_{11}}$    |                | $M_A = \frac{w}{2\beta^2} \frac{C_1 C_{a4} - C_3 C_{a2}}{C_{12}}$            | $M_A = \frac{w}{2\beta^2} \frac{C_2 C_{a5} - C_4 C_{a3}}{C_{13}}$        | $M_A = \frac{w}{2\beta^2} \frac{2C_3 C_{a5} - C_4 C_{a4}}{C_{11}}$           |                |

**TABLE 8.5 Shear, moment, slope, and deflection formulas for finite-length beams on elastic foundations (Continued)**

3. Partial uniformly increasing load



$$\text{Transverse shear} = V = R_A F_1 - y_A 2EI\beta^3 F_2 - \theta_A 2EI\beta^2 F_3 - M_A \beta F_4 - \frac{wF_{a3}}{2\beta^2(l-a)}$$

$$\text{Bending moment} = M = M_A F_1 + \frac{R_A}{2\beta} F_2 - y_A 2EI\beta^2 F_3 - \theta_A EI\beta F_4 - \frac{wF_{a4}}{4\beta^3(l-a)}$$

$$\text{Slope} = \theta = \theta_A F_1 + \frac{M_A}{2EI\beta} F_2 + \frac{R_A}{2EI\beta^2} F_3 - y_A \beta F_4 - \frac{wF_{a5}}{4EI\beta^4(l-a)}$$

$$\text{Deflection} = y = y_A F_1 + \frac{\theta_A}{2\beta} F_2 + \frac{M_A}{2EI\beta^2} F_3 + \frac{R_A}{4EI\beta^3} F_4 - \frac{wF_{a6}}{8EI\beta^5(l-a)}$$

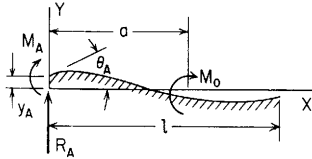
If  $\beta l > 6$ , see Table 8.6

Expressions for  $R_A$ ,  $M_A$ ,  $\theta_A$ , and  $y_A$  are found below for several combinations of end restraints

|                  | Right end  | Free  | Guided  | Simply supported   | Fixed   |   |
|------------------|--|---|---|--|---|---|
| Left end         | $R_A = 0$  | $M_A = 0$   | $R_A = 0$   | $M_A = 0$  | $R_A = 0$   | $M_A = 0$   |
| Free             | $\theta_A = \frac{w(C_2 C_{a4} - 2C_3 C_{a3})}{4EI\beta^4(l-a)C_{11}}$ | $\theta_A = \frac{w(C_2 C_{a5} - C_4 C_{a3})}{4EI\beta^4(l-a)C_{12}}$ | $\theta_A = \frac{w(C_1 C_{a4} + C_3 C_{a6})}{4EI\beta^4(l-a)C_{13}}$ | $\theta_A = \frac{w(2C_1 C_{a5} + C_4 C_{a6})}{4EI\beta^4(l-a)(2 + C_{11})}$ | $\theta_A = \frac{w(C_1 C_{a6} - C_2 C_{a5})}{4EI\beta^5(l-a)(2 + C_{11})}$ |   |
|                  | $y_A = \frac{w(C_4 C_{a3} - C_3 C_{a4})}{4EI\beta^5(l-a)C_{11}}$       | $y_A = \frac{-w(C_1 C_{a3} + C_3 C_{a5})}{4EI\beta^5(l-a)C_{12}}$     | $y_A = \frac{-w(C_2 C_{a4} + C_4 C_{a6})}{8EI\beta^5(l-a)C_{13}}$     | $y_A = \frac{-w(C_2 C_{a6} - C_3 C_{a4})}{8EI\beta^5(l-a)(1 + C_{11})}$      | $y_A = \frac{w(C_1 C_{a6} - C_2 C_{a5})}{4EI\beta^5(l-a)(2 + C_{11})}$      |   |
| Guided           | $R_A = 0$  | $\theta_A = 0$  | $R_A = 0$   | $\theta_A = 0$   | $R_A = 0$   | $\theta_A = 0$  |
|                  | $M_A = \frac{w(C_2 C_{a4} - 2C_3 C_{a3})}{4\beta^3(l-a)C_{12}}$        | $M_A = \frac{w(C_2 C_{a5} - C_4 C_{a3})}{4\beta^3(l-a)C_{14}}$        | $M_A = \frac{w(C_1 C_{a4} + C_3 C_{a6})}{4\beta^3(l-a)(1 + C_{11})}$  | $M_A = \frac{w(C_2 C_{a6} - C_3 C_{a4})}{8EI\beta^5(l-a)(1 + C_{11})}$       | $M_A = \frac{w(2C_1 C_{a5} + C_4 C_{a6})}{4\beta^3(l-a)C_{12}}$             | $M_A = \frac{w(C_2 C_{a6} - 2C_3 C_{a5})}{8EI\beta^5(l-a)C_{12}}$ |
| Simply supported | $M_A = 0$  | $y_A = 0$   | $M_A = 0$   | $y_A = 0$  | $M_A = 0$   | $y_A = 0$   |
|                  | $R_A = \frac{w(C_3 C_{a4} - C_4 C_{a3})}{2\beta^2(l-a)C_{13}}$         | $R_A = \frac{w(C_1 C_{a3} + C_3 C_{a5})}{2\beta^2(l-a)(1 + C_{11})}$  | $R_A = \frac{w(C_2 C_{a4} + C_4 C_{a6})}{4\beta^2(l-a)C_{14}}$        | $R_A = \frac{w(C_2 C_{a6} - C_3 C_{a4})}{8EI\beta^5(l-a)C_{14}}$             | $R_A = \frac{w(C_2 C_{a5} - C_1 C_{a6})}{2\beta^2(l-a)C_{13}}$              | $R_A = \frac{w(C_3 C_{a6} - C_4 C_{a5})}{4EI\beta^4(l-a)C_{13}}$  |
| Fixed            | $\theta_A = 0$   | $y_A = 0$   | $\theta_A = 0$  | $y_A = 0$  | $\theta_A = 0$  | $y_A = 0$   |
|                  | $R_A = \frac{w(2C_1 C_{a3} + C_4 C_{a4})}{2\beta^2(l-a)(2 + C_{11})}$  | $R_A = \frac{w(C_4 C_{a5} + C_2 C_{a3})}{2\beta^2(l-a)C_{12}}$        | $R_A = \frac{w(C_3 C_{a4} - C_1 C_{a6})}{2\beta^2(l-a)C_{13}}$        | $R_A = \frac{w(C_2 C_{a6} - C_4 C_{a4})}{4\beta^3(l-a)C_{13}}$               | $R_A = \frac{w(2C_3 C_{a5} - C_2 C_{a6})}{2\beta^2(l-a)C_{11}}$             | $R_A = \frac{w(C_3 C_{a6} - C_4 C_{a5})}{2\beta^3(l-a)C_{11}}$    |
|                  | $M_A = \frac{w(C_1 C_{a4} - C_2 C_{a3})}{2\beta^3(l-a)(2 + C_{11})}$   | $M_A = \frac{w(C_1 C_{a5} - C_3 C_{a3})}{2\beta^3(l-a)C_{12}}$        | $M_A = \frac{w(C_2 C_{a6} - C_4 C_{a4})}{4\beta^3(l-a)C_{13}}$        |  |   |   |

**TABLE 8.5 Shear, moment, slope, and deflection formulas for finite-length beams on elastic foundations (Continued)**

4. Concentrated intermediate moment



$$\text{Transverse shear} = V = R_A F_1 - y_A 2EI\beta^3 F_2 - \theta_A 2EI\beta^2 F_3 - M_A \beta F_4 - M_o \beta F_{a4}$$

$$\text{Bending moment} = M = M_A F_1 + \frac{R_A}{2\beta} F_2 - y_A 2EI\beta^2 F_3 - \theta_A EI\beta F_4 + M_o F_{a1}$$

$$\text{Slope} = \theta = \theta_A F_1 + \frac{M_A}{2EI\beta} F_2 + \frac{R_A}{2EI\beta^2} F_3 - y_A \beta F_4 + \frac{M_o}{2EI\beta} F_{a2}$$

$$\text{Deflection} = y = y_A F_1 + \frac{\theta_A}{2\beta} F_2 + \frac{M_A}{2EI\beta^2} F_3 + \frac{R_A}{4EI\beta^3} F_4 + \frac{M_o}{2EI\beta^2} F_{a3}$$

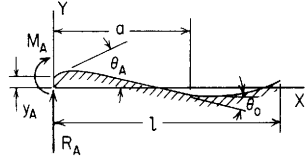
If  $\beta l > 6$ , see Table 8.6

Expressions for  $R_A$ ,  $M_A$ ,  $\theta_A$ , and  $y_A$  are found below for several combinations of end restraints

|                  | Right end | Free   | Guided  | Simply supported  | Fixed   |
|------------------|-----------|--|---|---|---|
| Left end         | Free      | $R_A = 0 \quad M_A = 0$  | $R_A = 0 \quad M_A = 0$   | $R_A = 0 \quad M_A = 0$   | $R_A = 0 \quad M_A = 0$   |
|                  |           | $\theta_A = \frac{-M_o C_3 C_{a4} + C_2 C_{a1}}{EI\beta C_{11}}$           | $\theta_A = \frac{-M_o C_2 C_{a2} + C_4 C_{a4}}{2EI\beta C_{12}}$             | $\theta_A = \frac{-M_o C_1 C_{a1} + C_3 C_{a3}}{EI\beta C_{13}}$          | $\theta_A = \frac{-M_o C_1 C_{a2} + C_4 C_{a3}}{EI\beta C_{12} + C_{11}}$   |
| Free             |           | $y_A = \frac{M_o}{2EI\beta^2} \frac{2C_3 C_{a1} + C_4 C_{a4}}{C_{11}}$     | $y_A = \frac{M_o}{2EI\beta^2} \frac{C_3 C_{a2} - C_1 C_{a4}}{C_{12}}$         | $y_A = \frac{M_o}{2EI\beta^2} \frac{C_4 C_{a3} + C_2 C_{a1}}{C_{13}}$     | $y_A = \frac{-M_o}{2EI\beta^2} \frac{2C_1 C_{a3} - C_2 C_{a2}}{2 + C_{11}}$ |
|                  | Guided    | $R_A = 0 \quad \theta_A = 0$   | $R_A = 0 \quad \theta_A = 0$  | $R_A = 0 \quad \theta_A = 0$  | $R_A = 0 \quad \theta_A = 0$  |
| Guided           |           | $M_A = -M_o \frac{C_2 C_{a1} + C_3 C_{a4}}{C_{12}}$                        | $M_A = \frac{-M_o C_2 C_{a2} + C_4 C_{a4}}{2 C_{14}}$                         | $M_A = -M_o \frac{C_1 C_{a1} + C_3 C_{a3}}{1 + C_{11}}$                   | $M_A = -M_o \frac{C_1 C_{a2} + C_4 C_{a3}}{C_{12}}$                         |
|                  |           | $y_A = \frac{-M_o}{2EI\beta^2} \frac{C_1 C_{a4} - C_4 C_{a1}}{C_{12}}$     | $y_A = \frac{M_o}{4EI\beta^2} \frac{C_4 C_{a2} - C_2 C_{a4}}{C_{14}}$         | $y_A = \frac{M_o}{2EI\beta^2} \frac{C_3 C_{a1} - C_1 C_{a3}}{1 + C_{11}}$ | $y_A = \frac{M_o}{2EI\beta^2} \frac{C_3 C_{a2} - C_2 C_{a3}}{C_{12}}$       |
| Simply supported |           | $M_A = 0 \quad y_A = 0$  | $M_A = 0 \quad y_A = 0$   | $M_A = 0 \quad y_A = 0$   | $M_A = 0 \quad y_A = 0$   |
|                  |           | $R_A = -M_o \beta \frac{2C_3 C_{a1} + C_4 C_{a4}}{C_{13}}$                 | $R_A = -M_o \beta \frac{C_3 C_{a2} - C_1 C_{a4}}{1 + C_{11}}$                 | $R_A = -M_o \beta \frac{C_2 C_{a1} + C_4 C_{a3}}{C_{14}}$                 | $R_A = -M_o \beta \frac{C_2 C_{a2} - 2C_1 C_{a3}}{C_{13}}$                  |
| Fixed            |           | $\theta_A = \frac{-M_o}{2EI\beta} \frac{2C_1 C_{a1} + C_2 C_{a4}}{C_{13}}$ | $\theta_A = \frac{-M_o}{2EI\beta} \frac{C_1 C_{a2} + C_3 C_{a4}}{1 + C_{11}}$ | $\theta_A = \frac{-M_o}{2EI\beta} \frac{C_2 C_{a3} - C_4 C_{a1}}{C_{14}}$ | $\theta_A = \frac{-M_o}{2EI\beta} \frac{2C_3 C_{a3} - C_4 C_{a2}}{C_{13}}$  |
|                  |           | $R_A = -M_o 2\beta \frac{C_4 C_{a1} - C_1 C_{a4}}{2 + C_{11}}$             | $R_A = -M_o \beta \frac{C_4 C_{a2} - C_2 C_{a4}}{C_{12}}$                     | $R_A = -M_o 2\beta \frac{C_3 C_{a1} - C_1 C_{a3}}{C_{13}}$                | $R_A = -M_o 2\beta \frac{C_3 C_{a2} - C_2 C_{a3}}{C_{11}}$                  |
| Fixed            |           | $\theta_A = 0 \quad y_A = 0$   | $\theta_A = 0 \quad y_A = 0$  | $\theta_A = 0 \quad y_A = 0$  | $\theta_A = 0 \quad y_A = 0$  |
|                  |           | $M_A = -M_o \frac{2C_1 C_{a1} + C_2 C_{a4}}{2 + C_{11}}$                   | $M_A = -M_o \frac{C_1 C_{a2} + C_3 C_{a4}}{C_{12}}$                           | $M_A = -M_o \frac{C_2 C_{a3} - C_4 C_{a1}}{C_{13}}$                       | $M_A = -M_o \frac{2C_3 C_{a3} - C_4 C_{a2}}{C_{11}}$                        |

TABLE 8.5 Shear, moment, slope, and deflection formulas for finite-length beams on elastic foundations (Continued)

5. Externally created concentrated angular displacement



$$\text{Transverse shear} = V = R_A F_1 - y_A 2EI\beta^3 F_2 - \theta_A 2EI\beta^2 F_3 - M_A \beta F_4 - \theta_0 2EI\beta^2 F_{a3}$$

$$\text{Bending moment} = M = M_A F_1 + \frac{R_A}{2\beta} F_2 - y_A 2EI\beta^2 F_3 - \theta_A EI\beta F_4 - \theta_0 EI\beta F_{a4}$$

$$\text{Slope} = \theta = \theta_A F_1 + \frac{M_A}{2EI\beta} F_2 + \frac{R_A}{2EI\beta^2} F_3 - y_A \beta F_4 + \theta_0 F_{a1}$$

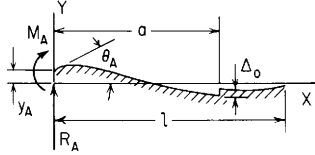
$$\text{Deflection} = y = y_A F_1 + \frac{\theta_A}{2\beta} F_2 + \frac{M_A}{2EI\beta^2} F_3 + \frac{R_A}{4EI\beta^3} F_4 + \frac{\theta_0}{2\beta} F_{a2}$$

If  $\beta l > 6$ , see Table 8.6Expressions for  $R_A$ ,  $M_A$ ,  $\theta_A$ , and  $y_A$  are found below for several combinations of end restraints

|                  | Right end | Free   | Guided   | Simply supported  | Fixed   |
|------------------|-----------|--|--|---|---|
| Left end         | Free      | $R_A = 0$ $M_A = 0$  | $R_A = 0$ $M_A = 0$  | $R_A = 0$ $M_A = 0$   | $R_A = 0$ $M_A = 0$   |
|                  |           | $\theta_A = \theta_0 \frac{C_2 C_{a4} - 2C_3 C_{a3}}{C_{11}}$            | $\theta_A = -\theta_0 \frac{C_2 C_{a1} + C_4 C_{a3}}{C_{12}}$          | $\theta_A = \theta_0 \frac{C_1 C_{a4} - C_3 C_{a2}}{C_{13}}$                | $\theta_A = -\theta_0 \frac{2C_1 C_{a1} + C_4 C_{a2}}{2 + C_{11}}$          |
|                  |           | $y_A = \frac{\theta_0}{\beta} \frac{C_4 C_{a3} - C_3 C_{a4}}{C_{11}}$    | $y_A = \frac{\theta_0}{\beta} \frac{C_3 C_{a1} - C_1 C_{a3}}{C_{12}}$  | $y_A = \frac{\theta_0}{\beta} \frac{C_4 C_{a2} - C_2 C_{a4}}{C_{13}}$       | $y_A = \frac{-\theta_0}{2\beta} \frac{C_1 C_{a2} - C_2 C_{a1}}{2 + C_{11}}$ |
| Guided           | Free      | $R_A = 0$ $\theta_A = 0$   | $R_A = 0$ $\theta_A = 0$   | $R_A = 0$ $\theta_A = 0$  | $R_A = 0$ $\theta_A = 0$  |
|                  |           | $M_A = \theta_0 EI\beta \frac{C_2 C_{a4} - 2C_3 C_{a3}}{C_{12}}$         | $M_A = -\theta_0 EI\beta \frac{C_2 C_{a1} + C_4 C_{a3}}{C_{14}}$       | $M_A = \theta_0 EI\beta \frac{C_1 C_{a4} - C_3 C_{a2}}{1 + C_{11}}$         | $M_A = -\theta_0 EI\beta \frac{2C_1 C_{a1} + C_4 C_{a2}}{C_{12}}$           |
|                  |           | $y_A = \frac{-\theta_0}{2\beta} \frac{2C_1 C_{a3} + C_4 C_{a4}}{C_{12}}$ | $y_A = \frac{\theta_0}{2\beta} \frac{C_4 C_{a1} - C_2 C_{a3}}{C_{14}}$ | $y_A = \frac{-\theta_0}{2\beta} \frac{C_1 C_{a2} + C_3 C_{a4}}{1 + C_{11}}$ | $y_A = \frac{\theta_0}{2\beta} \frac{2C_3 C_{a1} - C_2 C_{a2}}{C_{12}}$     |
| Simply supported | Free      | $M_A = 0$ $y_A = 0$  | $M_A = 0$ $y_A = 0$  | $M_A = 0$ $y_A = 0$   | $M_A = 0$ $y_A = 0$   |
|                  |           | $R_A = \theta_0 2EI\beta^2 \frac{C_3 C_{a4} - C_4 C_{a3}}{C_{13}}$       | $R_A = \theta_0 2EI\beta^2 \frac{C_1 C_{a3} - C_3 C_{a1}}{1 + C_{11}}$ | $R_A = \theta_0 EI\beta^2 \frac{C_2 C_{a4} - C_4 C_{a2}}{C_{14}}$           | $R_A = \theta_0 2EI\beta^2 \frac{C_1 C_{a2} - C_2 C_{a1}}{C_{13}}$          |
|                  |           | $\theta_A = \theta_0 \frac{C_1 C_{a4} - C_2 C_{a3}}{C_{13}}$             | $\theta_A = -\theta_0 \frac{C_1 C_{a1} + C_3 C_{a3}}{1 + C_{11}}$      | $\theta_A = \frac{-\theta_0}{2} \frac{C_2 C_{a2} + C_4 C_{a4}}{C_{14}}$     | $\theta_A = \theta_0 \frac{C_4 C_{a1} - C_3 C_{a2}}{C_{13}}$                |
| Fixed            | Free      | $\theta_A = 0$ $y_A = 0$   | $\theta_A = 0$ $y_A = 0$   | $\theta_A = 0$ $y_A = 0$  | $\theta_A = 0$ $y_A = 0$  |
|                  |           | $R_A = \theta_0 2EI\beta^2 \frac{2C_1 C_{a3} + C_4 C_{a4}}{2 + C_{11}}$  | $R_A = \theta_0 2EI\beta^2 \frac{C_2 C_{a3} - C_4 C_{a1}}{C_{12}}$     | $R_A = \theta_0 2EI\beta^2 \frac{C_1 C_{a2} + C_3 C_{a4}}{C_{13}}$          | $R_A = \theta_0 2EI\beta^2 \frac{C_2 C_{a2} - 2C_3 C_{a1}}{C_{11}}$         |
|                  |           | $M_A = \theta_0 2EI\beta \frac{C_1 C_{a4} - C_2 C_{a3}}{2 + C_{11}}$     | $M_A = -\theta_0 2EI\beta \frac{C_1 C_{a1} + C_3 C_{a3}}{C_{12}}$      | $M_A = -\theta_0 EI\beta \frac{C_2 C_{a2} + C_4 C_{a4}}{C_{13}}$            | $M_A = \theta_0 2EI\beta \frac{C_4 C_{a1} - C_3 C_{a2}}{C_{11}}$            |

TABLE 8.5 Shear, moment, slope, and deflection formulas for finite-length beams on elastic foundations (Continued)

6. Externally created concentrated lateral displacement



$$\text{Transverse shear} = V = R_A F_1 - y_A 2EI\beta^3 F_2 - \theta_A 2EI\beta^2 F_3 - M_A \beta F_4 - \Delta_0 2EI\beta^3 F_{a2}$$

$$\text{Bending moment} = M = M_A F_1 + \frac{R_A}{2\beta} F_2 - y_A 2EI\beta^2 F_3 - \theta_A EI\beta F_4 - \Delta_0 2EI\beta^2 F_{a3}$$

$$\text{Slope} = \theta = \theta_A F_1 + \frac{M_A}{2EI\beta} F_2 + \frac{R_A}{2EI\beta^2} F_3 - y_A \beta F_4 - \Delta_0 \beta F_{a4}$$

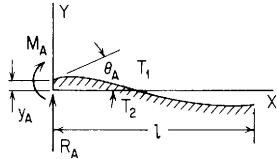
$$\text{Deflection} = y = y_A F_1 + \frac{\theta_A}{2\beta} F_2 + \frac{M_A}{4EI\beta^3} F_3 + \frac{R_A}{4EI\beta^3} F_4 + \Delta_0 F_{a1}$$

If  $\beta l > 6$ , see Table 8.6Expressions for  $R_A$ ,  $M_A$ ,  $\theta_A$ , and  $y_A$  are found below for several combinations of end restraints

|   | Right end   | Free   | Guided   | Simply supported   | Fixed   |           |
|---|---|--|--|--|---|-----------|
| Left end  | $R_A = 0$   | $M_A = 0$  | $R_A = 0$  | $M_A = 0$  | $R_A = 0$   | $M_A = 0$ |
| Free  | $\theta_A = \Delta_0 2\beta \frac{C_2 C_{a3} - C_3 C_{a2}}{C_{11}}$ |  | $\theta_A = \Delta_0 \beta \frac{C_2 C_{a4} - C_4 C_{a2}}{C_{12}}$ |  | $\theta_A = \Delta_0 2\beta \frac{C_1 C_{a3} - C_3 C_{a1}}{C_{13}}$ |           |
|   | $y_A = \Delta_0 \frac{C_4 C_{a2} - 2C_3 C_{a3}}{C_{11}}$            |  | $y_A = -\Delta_0 \frac{C_1 C_{a2} + C_3 C_{a4}}{C_{12}}$           |  | $y_A = \Delta_0 \frac{C_4 C_{a1} - C_2 C_{a3}}{C_{13}}$             |           |
| Guided  | $R_A = 0$   |  | $R_A = 0$  |  | $R_A = 0$   |           |
|   | $\theta_A = 0$  |  | $\theta_A = 0$   |  | $\theta_A = 0$  |           |
| $M_A = \Delta_0 2EI\beta^2 \frac{C_2 C_{a3} - C_3 C_{a2}}{C_{12}}$      |   | $M_A = \Delta_0 EI\beta^2 \frac{C_2 C_{a4} - C_4 C_{a2}}{C_{14}}$      |  | $M_A = \Delta_0 2EI\beta^2 \frac{C_1 C_{a3} - C_3 C_{a1}}{1 + C_{11}}$ |   |           |
| $y_A = -\Delta_0 \frac{C_1 C_{a2} + C_4 C_{a3}}{C_{12}}$                |   | $y_A = -\frac{\Delta_0}{2} \frac{C_2 C_{a2} + C_4 C_{a4}}{C_{14}}$     |  | $y_A = -\Delta_0 \frac{C_1 C_{a1} + C_3 C_{a3}}{1 + C_{11}}$           |   |           |
| Simply supported  | $M_A = 0$   |  | $M_A = 0$  |  | $M_A = 0$   |           |
|   | $y_A = 0$   |  | $y_A = 0$  |  | $y_A = 0$   |           |
| $R_A = \Delta_0 2EI\beta^3 \frac{2C_3 C_{a3} - C_4 C_{a2}}{C_{13}}$     |   | $R_A = \Delta_0 2EI\beta^3 \frac{C_1 C_{a2} + C_3 C_{a4}}{1 + C_{11}}$ |  | $R_A = \Delta_0 2EI\beta^3 \frac{C_2 C_{a3} - C_4 C_{a1}}{C_{14}}$     |   |           |
| $\theta_A = \Delta_0 \beta \frac{2C_1 C_{a3} - C_2 C_{a2}}{C_{13}}$     |   | $\theta_A = \Delta_0 \beta \frac{C_1 C_{a4} - C_3 C_{a2}}{1 + C_{11}}$ |  | $\theta_A = -\Delta_0 \beta \frac{C_2 C_{a1} + C_4 C_{a3}}{C_{14}}$    |   |           |
| Fixed   | $\theta_A = 0$  |  | $\theta_A = 0$   |  | $\theta_A = 0$  |           |
|   | $y_A = 0$   |  | $y_A = 0$  |  | $y_A = 0$   |           |
| $R_A = \Delta_0 4EI\beta^3 \frac{C_1 C_{a2} + C_4 C_{a3}}{2 + C_{11}}$  |   | $R_A = \Delta_0 2EI\beta^3 \frac{C_4 C_{a4} + C_2 C_{a2}}{C_{12}}$     |  | $R_A = \Delta_0 4EI\beta^3 \frac{C_3 C_{a3} + C_1 C_{a1}}{C_{13}}$     |   |           |
| $M_A = \Delta_0 2EI\beta^2 \frac{2C_1 C_{a3} - C_2 C_{a2}}{2 + C_{11}}$ |   | $M_A = \Delta_0 2EI\beta^2 \frac{C_1 C_{a4} - C_3 C_{a2}}{C_{12}}$     |  | $M_A = -\Delta_0 2EI\beta^2 \frac{C_2 C_{a1} + C_4 C_{a3}}{C_{13}}$    |   |           |
| $R_A = \Delta_0 4EI\beta^3 \frac{C_3 C_{a4} + C_2 C_{a1}}{C_{11}}$      |   | $R_A = \Delta_0 4EI\beta^3 \frac{C_3 C_{a4} + C_2 C_{a1}}{C_{11}}$     |  | $R_A = \Delta_0 4EI\beta^3 \frac{C_3 C_{a4} + C_2 C_{a1}}{C_{11}}$     |   |           |
| $M_A = -\Delta_0 2EI\beta^2 \frac{2C_3 C_{a1} + C_4 C_{a4}}{C_{11}}$    |   | $M_A = -\Delta_0 2EI\beta^2 \frac{2C_3 C_{a1} + C_4 C_{a4}}{C_{11}}$   |  | $M_A = -\Delta_0 2EI\beta^2 \frac{2C_3 C_{a1} + C_4 C_{a4}}{C_{11}}$   |   |           |

**TABLE 8.5 Shear, moment, slope, and deflection formulas for finite-length beams on elastic foundations (Continued)**

7. Uniform temperature differential from top to bottom



$$\text{Transverse shear} = V = R_A F_1 - y_A 2EI\beta^3 F_2 - \theta_A 2EI\beta^2 F_3 - M_A \beta F_4 + \frac{T_1 - T_2}{t} \gamma EI \beta F_4$$

$$\text{Bending moment} = M = M_A F_1 + \frac{R_A}{2\beta} F_2 - y_A 2EI\beta^2 F_3 - \theta_A EI \beta F_4 - \frac{T_1 - T_2}{t} \gamma EI (F_1 - 1)$$

$$\text{Slope} = \theta = \theta_A F_1 + \frac{M_A}{2EI\beta} F_2 + \frac{R_A}{2EI\beta^2} F_3 - y_A \beta F_4 - \frac{T_1 - T_2}{2t\beta} \gamma F_2$$

$$\text{Deflection} = y = y_A F_1 + \frac{\theta_A}{2\beta} F_2 + \frac{M_A}{2EI\beta^2} F_3 + \frac{R_A}{4EI\beta^3} F_4 - \frac{T_1 - T_2}{2t\beta^2} \gamma F_3$$

If  $\beta l > 6$ , see Table 8.6

Expressions for  $R_A$ ,  $M_A$ ,  $\theta_A$ , and  $y_A$  are found below for several combinations of end restraints

|                  | Right end  | Free   | Guided   | Simply supported  | Fixed  |
|------------------|--|--|--|---|--|
| Left end         | $R_A = 0$  | $M_A = 0$  | $R_A = 0$  | $M_A = 0$   | $R_A = 0$  |
|                  | $\theta_A = \frac{(T_1 - T_2)\gamma}{\beta t} \frac{C_1 C_2 + C_3 C_4 - C_2}{C_{11}}$  | $\theta_A = \frac{(T_1 - T_2)\gamma}{2\beta t} \frac{C_2^2 + C_4^2}{C_{12}}$         | $\theta_A = \frac{(T_1 - T_2)\gamma}{\beta t} \frac{C_1^2 + C_3^2}{C_{13}}$            | $\theta_A = \frac{(T_1 - T_2)\gamma}{\beta t} \frac{C_1 + C_3 - C_4}{C_{13}}$       | $\theta_A = \frac{(T_1 - T_2)\gamma}{2\beta^2 t} \frac{C_1 C_2 + C_3 C_4}{2 + C_{11}}$ |
| Free             | $y_A = \frac{-(T_1 - T_2)\gamma}{2\beta^2 t} \frac{C_4^2 + 2C_1 C_3 - 2C_3}{C_{11}}$   | $y_A = \frac{-(T_1 - T_2)\gamma}{2\beta^2 t} \frac{C_2 C_3 - C_1 C_4}{C_{12}}$       | $y_A = \frac{-(T_1 - T_2)\gamma}{\beta t} \frac{C_1 C_2 + C_3 C_4 - C_2}{C_{13}}$      | $y_A = \frac{-(T_1 - T_2)\gamma}{\beta t} \frac{C_1 C_2 + C_3 C_4 - C_2}{C_{13}}$   | $y_A = \frac{(T_1 - T_2)\gamma}{2\beta^2 t} \frac{2C_1 C_3 - C_2^2}{2 + C_{11}}$       |
| Guided           | $R_A = 0$  | $\theta_A = 0$   | $R_A = 0$  | $\theta_A = 0$  | $R_A = 0$  |
|                  | $M_A = \frac{(T_1 - T_2)\gamma EI}{t} \frac{C_1 C_2 + C_3 C_4 - C_2}{C_{12}}$          | $M_A = \frac{(T_1 - T_2)\gamma EI}{t}$   | $M_A = \frac{(T_1 - T_2)\gamma EI}{t} \frac{C_1^2 + C_3^2 - C_1}{1 + C_{11}}$          | $M_A = \frac{(T_1 - T_2)\gamma EI}{t} \frac{C_3}{1 + C_{11}}$                       | $M_A = \frac{(T_1 - T_2)\gamma EI}{t}$   |
|                  | $y_A = \frac{(T_1 - T_2)\gamma}{2\beta^2 t} \frac{C_4}{C_{12}}$                        | $y_A = 0$  | $y_A = \frac{(T_1 - T_2)\gamma}{2\beta^2 t} \frac{C_3}{1 + C_{11}}$                    | $y_A = 0$   | $y_A = 0$  |
| Simply supported | $M_A = 0$  | $y_A = 0$  | $M_A = 0$  | $y_A = 0$   | $M_A = 0$  |
|                  | $R_A = \frac{(T_1 - T_2)\gamma \beta EI}{t} \frac{2C_1 C_3 + C_4^2 - 2C_3}{C_{13}}$    | $R_A = \frac{(T_1 - T_2)\gamma \beta EI}{t} \frac{C_2 C_3 - C_1 C_4}{1 + C_{11}}$    | $R_A = \frac{(T_1 - T_2)\gamma \beta EI}{t} \frac{C_1 C_2 + C_3 C_4 - C_2}{C_{14}}$    | $R_A = \frac{(T_1 - T_2)\gamma \beta EI}{t} \frac{C_2 C_3 - C_1 C_4 + C_4}{C_{14}}$ | $R_A = \frac{(T_1 - T_2)\gamma \beta EI}{t} \frac{C_2^2 - 2C_1 C_3}{C_{13}}$           |
|                  | $\theta_A = \frac{(T_1 - T_2)\gamma}{2\beta t} \frac{2C_1^2 + C_2 C_4 - 2C_1}{C_{13}}$ | $\theta_A = \frac{(T_1 - T_2)\gamma}{2\beta t} \frac{C_1 C_2 + C_3 C_4}{1 + C_{11}}$ | $\theta_A = \frac{(T_1 - T_2)\gamma}{2\beta t} \frac{C_2 C_3 - C_1 C_4 + C_4}{C_{14}}$ | $\theta_A = \frac{(T_1 - T_2)\gamma}{2\beta t} \frac{2C_3^2 - C_2 C_4}{C_{13}}$     | $\theta_A = \frac{(T_1 - T_2)\gamma}{2\beta t} \frac{2C_3^2 - C_2 C_4}{C_{13}}$        |
| Fixed            | $\theta_A = 0$   | $y_A = 0$  | $\theta_A = 0$   | $y_A = 0$   | $\theta_A = 0$   |
|                  | $R_A = \frac{(T_1 - T_2)\gamma 2\beta EI}{t} \frac{-C_4}{2 + C_{11}}$                  | $R_A = 0$  | $R_A = \frac{(T_1 - T_2)\gamma \beta EI}{t} \frac{-2C_3}{C_{13}}$                      | $R_A = 0$   | $R_A = 0$  |
|                  | $M_A = \frac{(T_1 - T_2)\gamma EI}{t} \frac{2C_1^2 + C_2 C_4 - 2C_1}{2 + C_{11}}$      | $M_A = \frac{(T_1 - T_2)\gamma EI}{t}$   | $M_A = \frac{(T_1 - T_2)\gamma EI}{t} \frac{C_2 C_3 - C_1 C_4 + C_4}{C_{13}}$          | $M_A = \frac{(T_1 - T_2)\gamma EI}{t}$  | $M_A = \frac{(T_1 - T_2)\gamma EI}{t}$   |